Standard Automation Interface (SAI)

APW Products





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1 SAI for APW Products

This manual covers all APW scales that currently support the Standard Automation Interface (SAI) protocol. All firmware versions of WMF and SPE support SAI. Please note that firmware version >= 3.0.4 is required for the SPC to support SAI.

1.1. Device Status Bits

The device status is a composite status word that contains individual bits to indicate the state of various scale or device specific binary values. The 16 bits include the following information:

| Bit | Device Specific Value | Description | WMF | SPC | SPE |
|-----|----------------------------------|--|-----|-----|-----|
| 0 | Sequence bit 0 Sequence bit 1 | Used as sequence toggle bits. When commands are sent by the control system, the device changes the value of the sequence bits as an indication that the command has been seen and acted on. Sequence bits are used during a sequence of commands to ensure that there have been no sequencing errors in the request and the response of data. They are updated on every new command. Binary value starts at zero and increments by one. Once the maximum value (binary = 11, decimal = 3) is reached, the next command causes the sequence bits to revert to zero. | X | X | Х |
| 2 | Heart Beat | Toggles between 0 and 1 (1 sec.) to ensure that the device is operational and updating data in Words 0, 1 and 2. | | Х | Х |
| 3 | Data OK | This bit is set to 1 when the device is operational and must be evaluated in conjunction with bit 4 (Smart5 Red) below. METTLER TOLEDO sample programs evaluate both bits simultaneously to indicate that the weight is valid. This bit gets set to 0 when the device is still operational, but the value being reported cannot be guaranteed to be valid. The following conditions cause the Data OK bit to be set to 0: Device is powering up Device is in setup mode Device is in test mode Over capacity condition occurs When the A/D converter is at its limit Product dependent over capacity that occurs when the device determines it cannot trust the weight | X | X | Х |

| Bit | Device Creatific Value | Description | WMF | U | Ш |
|-----|--|---|-----|-----|-----|
| DIL | Device Specific Value | Description | ≥ | SPC | SPE |
| | | Under capacity condition occurs When the A/D converter is at its limit | | | |
| | | Product dependent under capacity that occurs | | | |
| | | when the device determines it cannot trust the weight | | | |
| 4 | RedAlert Alarm Condition Smart5 Red Level 5 | The alarm condition indicates a system error. More information about the specific alarm can be found section 1.2, RedAlert Alarms. | Х | Х | Х |
| | | Application fault; predictive diagnostics alarm triggered or command cannot be executed as requested. It indicates that the control device must stop operating until the source of the alarm is evaluated and the cause of the alarm corrected. | | | |
| 5 | Center of Zero | 1 = Gross weight value is at a value of zero +/- one quarter of a weight and measures verification interval denoted as "e". | Х | Х | Х |
| 6 | Motion | 1 = Weight is unstable. The sensitivity of the motion condition is configured in the device and is additionally influenced by the filter settings. | Х | Х | Х |
| 7 | Net Mode | 1 = Net weight instead of gross weight is reported. | Х | Х | Х |
| 8 | Alternate weight unit | 1 = An alternate weight unit, other than the primary unit is in use. | Х | Х | Х |
| 9 | Reserved 1 | See SAI manual: 30588288 | | | |
| 10 | Smart5 Orange Level 4 | | | | |
| 11 | Smart5 Yellow Level 3 | These bits are used to provide device specific status information e.g. I/O or application status. No devices covered by this manual | | | |
| 12 | Smart5 Blue Level 2 | currently support device specific bits | | | |
| 13 | Selected Scale | | | | |
| 14 | Device Specific bit 6 |] | | | |
| 15 | Device Specific bit 7 | | | | |

1.2. RedAlert[™] Smart5[™] Alarms

The critical alarm status bits are sent as part of the default status block when a status block command 0 is sent. If the control system does not place any data in the command word (write), the device will send the data of RedAlert group. The 16 bits include the following information:

| Bit | Red Alert | Description | WMF | SPC | SPE |
|-----|---|--|-----|-----|-----|
| 0 | Calibration alarm | 1 = Weight data can no longer be trusted due to loss of calibration data or an algorithm running in the product to detect weighing irregularities. | ~ | SI | 12 |
| 1 | Out of A/D range over/under | 1 = Weight data can no longer be trusted due to loss of data or mechanical damage of the weigh module. | Х | Х | Х |
| 2 | Checksum failure | 1 = A checksum analysis of memory does not yield the expected result. | | | |
| 3 | Weight blocked | 1 = Weight data does not change appreciably over a defined period of time. | | | |
| 4 | Single sensor communication failure (LC missing) | 1 = One or more of the connected sensors are not working properly. | | | |
| 5 | Customer defined overload | Weight is equal to or greater than the maximum load allowed. Although overload is a conditional limit, it can lead to bigger errors such as mechanical breakage or personal injury. | | | |
| 6 | Customer defined underload | 1 = Weight is equal or less than the minimum load allowed. | | | |
| 7 | Network failure (all cells) | Applicable only on multi-cell networks. 1 = Failure of the entire network. No cells are responding. | | | |
| 8 | Zero out of range | 1 = A control system attempted a zero command, but the device did not accept the command because the weight is outside the specified limits or the weights and measure limits. | | | |
| 9 | Symmetry alarm | Applicable only for products with TraxDSP function which detects significant errors between load cells and their peers. 1 = A symmetry error has been detected. | | | |
| 10 | Temperature errors (LC temperature out of normal temperature) | 1 = Sensor is outside of the allowed temperature range. The weight value can be affected, or the components can prematurely fail. This bit goes high when Application Specific Bit 3 or 4 is activated (Section 1.4.1) | Х | Х | Х |
| 11 | Weights and measures failure | 1 = The product is no longer in compliance with weights and measure regulations. | Х | Х | Х |
| 12 | Foreign device detected | 1 = A foreign device is attached to the system or any similar algorithm limits. | | | |
| 13 | Test mode | 1 = Device is in a mode in which live data is being replaced with special test data. | Х | Х | Х |
| 14 | Analog Scale Failure (ACM) | 1 = Temperature for at least one loadcell is outside the operation temperature range | | | |
| 15 | Reserved | 1 = Checksum error occurred with loadcell parameters block | | | |

1.3. Scale Group 2

These status bits are sent as part of the default status block when a status block command 0 is sent. If the control system does not place any data in the command word (write), the device will send this data in scale status group. The 16 bits include the following information:

| Bit | Scale Status Group | Description | WMF | SPC | SPE |
|-----|-----------------------------------|--|-----|-----|-----|
| 0 | Unit bit 1 | Unit bits are used to indicate the weight unit. Refer to | Х | Х | Х |
| 1 | Unit bit 2 | section 1.3.1, Unit Bits , for more information. | | | |
| 2 | Unit bit 3 | | | | |
| 3 | Unit bit 4 | | | | |
| 4 | MinWeigh Error | 1 = Scale is below acceptable minimum weighing range. | | | |
| 5 | Range bit 1 | Range bits are used to indicate weight range or interval | | | |
| 6 | Range bit 2 | based on the values shown. Refer to section 1.3.2, Range Bits , for more information. | | | |
| 7 | In Set Up | 1 = Sensor is in setup mode. | Х | Х | Х |
| 8 | Power Up Zero Failure | 1 = Scale has not been able to complete its power-up restore / reset of zero. This condition usually indicates that the customer must remove an object from the scale before operating it. | Х | Х | Х |
| 9 | Reserved | | | | |
| 10 | Selected Scale | For multi-scale devices only: 1 = Scale is selected and therefore in focus or seen on the device display. | Х | Х | Х |
| 11 | Open | Unused (always 0) | | | |
| 12 | Open | | | | |
| 13 | Legal for Trade Switch Enabled | | | | |
| 14 | Open | | | | |
| 15 | Open | | | | |

1.3.1. Unit Bits

| Unit Bit 4 | Unit Bit 3 | Unit Bit 2 | Unit Bit 1 | Value |
|------------|------------|------------|------------|----------|
| 0 | 0 | 0 | 0 | g |
| 0 | 0 | 0 | 1 | kg |
| 0 | 0 | 1 | 0 | lb |
| 0 | 0 | 1 | 1 | t |
| 0 | 1 | 0 | 0 | ton |
| 0 | 1 | 0 | 1 | mg |
| 0 | 1 | 1 | 0 | ug |
| 0 | 1 | 1 | 1 | Custom |
| 1 | 0 | 0 | 0 | OZ |
| 1 | 0 | 0 | 1 | dwt |
| 1 | 0 | 1 | 0 | ozt |
| 1011-1111 | | | | Reserved |

1.3.2. Range Bits

| Range bit 2 | Range bit 1 | Value |
|-------------|-------------|------------------|
| 0 | 0 | Range/Interval 1 |
| 0 | 1 | Range/Interval 2 |
| 1 | 0 | Range/Interval 3 |
| 1 |] | Reserved |

1.4. Status Group 2 – Alarms

The application alarm status bits are set if the status block command "21" is sent. Otherwise, scale status group 2 information will be displayed.

| | | | WMF | U | ш |
|-----|----------------------------|---|-----|-----|-----|
| Bit | Soft Alarm | Description | Š | SPC | SPE |
| 0 | Rate of change | Product, application, or customer defines a weight / time | | | |
| | | scenario as a method of assurance that the scale is detecting weight | | | |
| 1 | Communication errors | 1 = The communication of a device which is connected to a sensor is not working according to specification. | | | |
| 2 | Over and under voltage (s) | A device which supports dynamic measurements of system power has over or under voltage. | | | |
| 3 | Weight drift | A strain gauge sensor has either a broken bridge or is damaged by water or lightning. | | | |
| 4 | Breach | 1 = The enclosure of the sensor has been compromised and is therefore vulnerable to environmental influences, e.g. moisture or water. In most cases, a failure will occur if the breach is not corrected or if the sensor is not replaced. | | | |
| 5 | Calibration expired | 1 = The maximum number of transactions or a time limit before a preventive service or recalibration has been reached. The alarm will toggle on N+1 weighing transactions. | | | |
| 6 | Application defined 0 | Refer to section 1.4.1, Application-Specific Soft | | | |
| 7 | Application defined 1 | Alarms, for more information. | Х | Х | Х |
| 8 | Application defined 2 | | | | |
| 9 | Application defined 3 | | Х | Х | Х |
| 10 | Application defined 4 | | | Х | |
| 11 | Application defined 5 | | | | |
| 12 | Application defined 6 | | Х | Х | Х |
| 13 | Application defined 7 | | | Х | |
| 14 | Application defined 8 | | | | |
| 15 | Application defined 9 | | | | |

1.4.1. Application-Specific Soft Alarms

| | WMF | SPC | SPE |
|--------------------------|---|---|--|
| Application Defined 0 | None | None | None |
| Application Defined 1 | Error – System general | Error – System General | Error – System General |
| Application Defined 2 | None | None | None |
| Application Defined 3 | Error – Temperature (weight sensor) | Error – Temperature (weight sensor) | Error - Temperature (weight sensor) |
| Application Defined 4 | None | Error – Temperature (electronic unit) | None |
| Application Defined 5 | None | None | None |
| Application Defined 6 | Warning – Temperature (weight sensor) | Warning – Temperature (weight sensor) | Warning – Temperature (weight sensor) |
| Application Defined 7 | None | Warning – Temperature (electronic unit) | None |
| Application Defined 8 | None | None | None |
| Application Defined 9 | None | None | None |

1.5. I/O Status Groups

On devices which support physical I/O, the status groups contain a combination of input and output status bits for I/O. Devices which do not support physical I/O, may have variables and logic to virtually represent inputs and outputs within the device. If the device does not support I/O groups, an invalid command response is sent for any supported I/O groups. The input and output status bits reflect the state of the associated inputs and outputs, 1 = on, 0 = off

| Bit | Data | WMF | SPC | SPE |
|-----|-------|-----|-----|-----|
| 0 | In 1 | | | |
| 1 | In 2 | Х | Х | Х |
| 2 | In 3 | | | |
| 3 | In 4 | | | |
| 4 | In 5 | | | |
| 5 | In 6 | | | |
| 6 | In 7 | | | |
| 7 | ln 8 | | | |
| 8 | Out 1 | | | |
| 9 | Out 2 | | | |
| 10 | Out 3 | | | |
| 11 | Out 4 | | | |
| 12 | Out 5 | | | |
| 13 | Out 6 | | | |
| 14 | Out 7 | | | |
| 15 | Out 8 | | | |

In 2: 1 = Gross weight is above target weight (limit can be set by cyclic command 220 and read by 20)

1.6.

SAI Status Block Command List

| Value | Description | WMF | SPC | SPE |
|-------|--|-----|-----|-----|
| 0 | Report default status words | Х | Х | Х |
| 1 | Report RedAlert Smart5 alarm, scale group, I/O group | Х | Х | Х |
| 2 | Report target / Comparator status | | | |
| 4 | Report Target 1, I/O group 2, custom application group 2 | | | |
| 16 | Report comparator mix 1 | | | |
| 21 | Report RedAlert Smart5 alarms, alarms & scale group 2 | Х | Х | Х |
| 23 | Report alarm status, I/O status, customer application status | | | |
| 100 | Report last error code | | | |

1.7. Cyclic Command List for Floating Point Block

| Mahaa | Description | Dissis | WMF | SPC | SPE |
|-------|---|----------------|--------|-----|-----|
| Value | Description | Block | - | | |
| 0 | Gross weight – rounded | Floating Block | X | X | Х |
| 1 | Gross weight – rounded | Floating Block | X | X | X |
| 2 | Tare weight – rounded | Floating Block | Х | Х | Х |
| 3 | Net weight – rounded | Floating Block | Х | Х | Х |
| 5 | Gross weight - internal resolution (Displays a maximum of 8 digits) | Floating Block | Х | х | Х |
| 6 | Tare weight - internal resolution (Displays a maximum of 8 digits) | Floating Block | Х | х | Х |
| 7 | Net weight - internal resolution (Displays a maximum of 8 digits) | Floating Block | х | х | Х |
| 14 | Net weight - alternative weight path (rounded) | Floating Block | Х | Х | Х |
| 20 | Read target weight (display unit) | Floating Block | Х | Х | Х |
| 82 | Report adjustment and test stability time [s] | Floating Block | ≥3.0.2 | Х | Х |
| 83 | Report general stability timeout [s] Parameter: 0 – 65535 Seconds | Floating Block | х | х | Х |
| 84 | Report observation time for zero Parameter : 0.1 – 4.0 Seconds | Floating Block | х | Х | Х |
| 85 | Report stability limit for zero Parameter : 0.1 – 1000 smallest actual scale interval | Floating Block | х | Х | Х |
| 86 | Report observation time for tare Parameter : 0.1 – 4.0 Seconds | Floating Block | х | Х | Х |
| 87 | Report stability limit for tare Parameter : 0.1 – 1000 smallest actual scale interval | Floating Block | Х | Х | Х |
| 88 | Report observation time for weighing Parameter : $0.1 - 4.0$ Seconds | Floating Block | х | Х | Х |
| 89 | Report stability limit for weighing Parameter : 0.1 – 1000 smallest actual scale interval | Floating Block | Х | Х | Х |
| 90 | Report current weighing mode Parameter: 0 = Universal Weighing (Normal Weighing) 2 = Fixed Filter (Sensor Mode) | Floating Block | х | Х | Х |

| Value | Description | Block | WMF | SPC | SPE |
|-------|--|----------------|--------|-----|-----|
| 91 | Report current weighing environment condition settings Parameter: 0 = Very Stable 1 = Stable 2 = Standard 3 = Unstable 4 = Very Unstable | Floating Block | х | Х | x |
| 92 | Report cut-off frequency of the fixed filter Parameter : 0 = Predefined frequency used, changeable over weighing environment 0.001 Hz - 20.0 Hz = Cutoff Frequency | Floating Block | х | х | х |
| 96 | Indication scale interval increase relative to the actual scale interval Parameter: 0 = Factor 1 1 = Factor 10 2 = Factor 100 3 = Factor 1000 4 = Factor 2 5 = Factor 5 | Floating Block | х | х | х |
| 97 | Internal temperature in °C | Floating Block | Х | Х | Х |
| 98 | Report cut-off frequency of the alternative weighing path filter | Floating Block | Х | Х | Х |
| 99 | Report stability limit for Adjustment and Test [d] | Floating Block | ≥3.0.2 | Х | Х |
| 142 | Read External Adjustment Weight | Floating Block | Х | Х | Х |
| 143 | Report Date and Time (in Unix timestamp) | Floating Block | ≥4.1.0 | Х | |
| 201 | Preset tare (display unit) Parameter: Pre-tare weight (float 32) placed in floating point value | Floating Block | Х | Х | х |
| 220 | Write target weight (display unit) | Floating Block | Х | Х | Х |
| 282 | Write Adjustment stability time [s] | Floating Block | ≥3.0.2 | Х | Х |
| 283 | Write general stability timeout [s] Parameter: 0 – 65535 Seconds | Floating Block | х | Х | х |
| 284 | Write observation time for zero Parameter: 0.1 – 4.0 Seconds | Floating Block | х | Х | х |
| 285 | Write stability limit for zero Parameter: 0.1 – 1000 smallest actual scale interval | Floating Block | Х | Х | х |
| 286 | Write observation time for tare Parameter: 0.1 – 4.0 Seconds | Floating Block | Х | Х | х |
| 287 | Write stability limit for tare Parameter: 0.1 – 1000 smallest actual scale interval | Floating Block | Х | Х | х |
| 288 | Write observation time for weighing Parameter : $0.1 - 4.0$ Seconds | Floating Block | Х | Х | х |

| Value | Description | Block | WMF | SPC | SPE |
|-------|--|----------------|--------|-----|-----|
| 289 | Write tolerance for weighing Parameter: 0.1 – 1000 smallest actual scale interval | Floating Block | Х | Х | х |
| 290 | Write weighing mode Parameter: 0 = Universal Weighing (Normal Weighing) 2 = Fixed Filter (Sensor Mode) | Floating Block | х | х | х |
| 291 | Write weighing environment Parameter: 0 = Very Stable 1 = Stable 2 = Standard 3 = Unstable 4 = Very Unstable | Floating Block | х | х | х |
| 292 | Write filter cut-off frequency Parameter: 0 = Predefined frequency used, changeable over weighing environment 0.001 Hz - 20.0 Hz = Cutoff Frequency | Floating Block | х | х | х |
| 296 | Write weight readability Parameter: 0 = 1 digit 1 = 10 digits 2 = 100 digits 3 = 1000 digits 4 = 2 digits 5 = 5 digits | Floating Block | x | х | х |
| 298 | Write filter cut-off frequency for alternative weighing path | Floating Block | Х | Х | Х |
| 299 | Write adjustment stability digit [d] | Floating Block | ≥3.0.2 | Х | Х |
| 342 | Write External Adjustment Weight | Floating Block | Х | Х | Х |
| 343 | Write Date and Time | Floating Block | ≥4.1.0 | Х | |
| 400 | Tare when stable | Floating Block | Х | Х | Х |
| 401 | Zero when stable | Floating Block | Х | Х | Х |
| 402 | Clear tare | Floating Block | Х | Х | Х |
| 403 | Tare immediately | Floating Block | Х | Х | Х |
| 404 | Zero immediately | Floating Block | Х | Х | Х |
| 1900 | Alarm bit – Test Mode | Floating Block | Х | Х | Х |
| 1901 | Motion bit – Test Mode | Floating Block | Х | Х | Х |
| 1902 | Net mode bit – Test Mode | Floating Block | Х | Х | Х |
| 1903 | Center of zero bit – Test Mode | Floating Block | Х | Х | Х |
| 1904 | Alt weight bit – Test Mode | Floating Block | Х | Х | Х |
| 1905 | Device bit 1 – Test Mode | Floating Block | Х | Х | Х |
| 1906 | Device bit 2 – Test Mode | Floating Block | Х | Х | Х |
| 1907 | Device bit 3 – Test Mode | Floating Block | Х | Х | Х |
| 1908 | Device bit 4 – Test Mode | Floating Block | Х | Х | Х |

| Value | Description | Block | WMF | SPC | SPE |
|-------|---|----------------|-----|-----|-----|
| 1909 | Device bit 5 – Test Mode | Floating Block | Х | Х | Х |
| 1910 | Device bit 6 – Test Mode | Floating Block | Х | Х | Х |
| 1911 | Device bit 7 – Test Mode | Floating Block | Х | Х | Х |
| 1912 | Performance test value | Floating Block | Х | Х | Х |
| 2000 | No operation command – used to test command | | Х | Х | Х |
| 2004 | Abort sequence response value means abort in process | | Х | х | Х |
| 2046 | Step successful | | Х | Х | Х |
| 2047 | Command has been received and is being evaluated (in process) | | Х | х | Х |

1.8. Acyclic Command List

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|------------------------------------|--|------------|-----------|----------------|---------------------|-----------------|-------------------------|----------------|---------|-----|-----|
| Gross weight - rounded | Gross weight data in displayed unit | read | Float 32 | 0x300 | 0x01 | 0x01 | 0, 1 | 0x2000 | Х | Х | Х |
| Gross weight - rounded | Gross weight data in displayed unit | read | Float 32 | 0x300 | 0x01 | 0x02 | 0, 1 | 0x2001 | Х | Х | Х |
| Tare weight - rounded | Tare weight data in displayed unit | read | Float 32 | 0x300 | 0x01 | 0x03 | 0, 1 | 0x2002 | Х | Х | Х |
| Net weight - rounded | Net weight data in displayed unit | read | Float 32 | 0x300 | 0x01 | 0x04 | 0, 1 | 0x2003 | Х | Х | Х |
| Gross weight - internal resolution | Gross weight data in internal resolution, Displays a maximum of 8 digits (weight after postprocessing in active unit) | read | Float 32 | 0x300 | 0x01 | 0x05 | 0, 1 | 0x2004 | х | Х | х |
| Tare weight - internal resolution | Tare weight data in internal resolution, Displays a maximum of 8 digits (weight after postprocessing in active unit | read | Float 32 | 0x300 | 0x01 | 0x06 | 0, 1 | 0x2005 | х | Х | х |
| Net weight - internal resolution | Net weight data in internal resolution, Displays a maximum of 8 digits (weight after postprocessing in active unit | read | Float 32 | 0x300 | 0x01 | 0x07 | 0, 1 | 0x2006 | Х | Х | Х |
| Tare procedure status bits | Report Tare operation status (used when triggering tare from acyclic interface) Parameter : 0 = tare procedure complete 1 = tare procedure in process | read | Uint 16 | 0x300 | 0x01 | 0x16 | 0, 1 | 0x2008 | ≥V3.0.2 | Х | х |
| Zero procedure status bits | Report Zero operation status (used when triggering zero from acyclic interface) Parameter : 0 = zero procedure complete 1 = zero procedure in process | read | Uint 16 | 0x300 | 0x01 | 0x17 | 0, 1 | 0x2009 | ≥V3.0.2 | Х | х |

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|--|---|----------------|---------------|----------------|---------------------|-----------------|-------------------------|----------------|---------|-----|-----|
| Tare when stable | Tare when weight value is within stability limit for the observation time | write | Uint 8 | 0x300 | 0x01 | 0x09 | 0, 1 | 0x2010 | Х | Х | х |
| Tare immediately | Motion not checked; tare executed | write | Uint 8 | 0x300 | 0x01 | 0x10 | 0, 1 | 0x2011 | Х | Х | Х |
| Clear tare | Motion not checked; clear tare executed | write | Uint 8 | 0x300 | 0x01 | Ox11 | 0, 1 | 0x2012 | Х | Х | Х |
| Zero when stable | Zero when weight value is within stability limit for the observation time | write | Uint 8 | 0x300 | 0x01 | 0x14 | 0, 1 | 0x2013 | Х | х | Х |
| Zero immediately | Motion not checked, zero executed | write | Uint 8 | 0x300 | 0x01 | 0x15 | 0, 1 | 0x2014 | Х | Х | Х |
| Preset tare (display unit) | Write tare register (Preset Tare) Parameter: Pre-tare weight | Read/ write | Float 32 | 0x300 | 0x01 | 0x08 | 0, 1 | 0x2020 | х | х | Х |
| Model type part 1 | Identification (main ID) | read | String 160 | 0x303 | 0x01 | 0x01 | 0, 1 | 0x2050 | Х | х | Х |
| Software OS version | Software OS Version | read | String 160 | 0x303 | 0x01 | 0x04 | 0, 1 | 0x2053 | Х | х | Х |
| Fieldbus stack version | Fieldbus Stack Version | read | String 160 | 0x303 | 0x01 | 0x05 | 0, 1 | 0x2054 | Х | Х | Х |
| Software application version | Software Apps Version | read | String 160 | 0x303 | 0x01 | 0x06 | 0, 1 | 0x2055 | Х | Х | Х |
| SAI version | SAI specification version number | read | String 160 | 0x303 | 0x01 | 0x07 | 0, 1 | 0x2056 | Х | х | Х |
| Serial number | Device main serial number | read | String 160 | 0x303 | 0x01 | 0x08 | 0, 1 | 0x2057 | ≥V3.0.2 | Х | Х |
| Get initial zero information | Receive initial zero operation status and the switch on range limit status. Load on the weight receptor must be within the switch on range limits for successful initialization. | read | Struct 16 | 0x303 | 0x01 | 0x11 | 0, 1 | 0x205A | ≥V4.1.0 | х | |
| Start adjustment with internal weight | Start Internal Adjustment – Relative calibration deviation (%) | write | Uint 8 | 0x410 | 0x01 | 0x01 | 0, 1 | 0x4001 | Х | | Х |

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|---|--|----------------|-----------|----------------|---------------------|-----------------|-------------------------|----------------|-----|-----|-----|
| Start adjustment with external weight | Start External Adjustment – Relative calibration deviation (%) | write | Uint 8 | 0x410 | 0x01 | 0x02 | 0, 1 | 0x4002 | Х | Х | х |
| Start customer standard calibration | Start User Standard Adjustment - defines the exact weight value of the built-in weights. | write | Uint 8 | 0x410 | 0x01 | 0x03 | 0, 1 | 0x4003 | Х | Х | х |
| Cancel adjustment / test (Abort Test Function / Adjustment) | Abort Test Function / Adjustment | write | Uint 8 | 0x410 | 0x01 | 0x04 | 0, 1 | 0x4004 | Х | х | х |
| Start test with internal weight | Start Sensitivity Test Function with internal weight. Absolute Deviation related to nominal load, in definition unit (g). | write | Uint 8 | 0x410 | 0x01 | 0x05 | 0, 1 | 0x4005 | Х | | х |
| Start test with external weight | Start Test Function with external weight. External weight defined with the 'External Test Weight' Command. Absolute Deviation related to nominal load, in definition unit (g). | write | Uint 8 | 0x410 | Ox01 | 0x06 | 0, 1 | 0x4006 | х | x | х |
| Adjustment and test status Information | Adjustment / Test status | read | Uint 16 | 0x410 | 0x01 | 0x07 | 0, 1 | 0x4007 | Х | Х | х |
| Test deviation | Adjustment / Test value: If 'Test' is executed, absolute deviation related to nominal load, in definition unit (g) If 'Adjustment' is executed, relative deviation (%) | read | Float 32 | 0x410 | 0x01 | 0x08 | 0, 1 | 0x4008 | х | Х | х |
| External adjustment weight | Set external adjustment weight and start adjustment. Parameter: Weight in unit selected according to Scale Status Group 2 | Read/ write | Float 32 | 0x410 | 0x01 | 0x09 | 0, 1 | 0x4009 | Х | х | x |
| Requested weight | Get currently requested external calibration weight during ongoing adjustment or calibration procedure | read | Float 32 | 0x410 | 0x01 | Ox11 | 0, 1 | 0x4011 | Х | Х | Х |

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|--|--|----------------|-----------|----------------|---------------------|-----------------|-------------------------|----------------|---------|-----|-----|
| External test weight | Set external calibration test weight unless default shall be used. Parameter: Weight in unit selected according to Scale Status Group 2 | write | Float 32 | 0x410 | 0x01 | 0x12 | 0, 1 | 0x4012 | x | х | х |
| Start test Function with internal weight | Start Test Function with internal weight - Relative calibration deviation (%) | Write | Uint 8 | 0x410 | 0x01 | 0x24 | 0, 1 | 0x4024 | ≥V4.1.0 | | |
| Internal temperature | Query the load cell temperature value (°C) | read | Float 32 | 0x413 | 0x01 | 0x19 | 0, 1 | 0x4169 | Х | Х | Х |
| Weighing mode | Weighing filter mode Parameter: 0 = Universal weighing (Normal Weighing) 2 = Fixed Filter (Sensor Mode) | read/ write | Float 32 | 0x415 | 0x01 | 0x06 | 0, 1 | 0x4256 | x | х | х |
| Weighing environment | Current environment condition settings Parameter: 0 = Very stable 1 = Stable 2 = Standard 3 = Unstable 4 = Very unstable | read/ write | Float 32 | 0x415 | 0x01 | 0x07 | 0, 1 | 0x4257 | X | х | Х |
| Cut-off frequency | Cut-Off frequency of the fixed filter Parameter: 0 = Pre-defined frequency used, changeable over weighing environment 0.001 Hz - 20.0 Hz = Cut-off frequency | read/ write | Float 32 | 0x415 | 0x01 | 0x08 | 0, 1 | 0x4258 | x | х | х |
| Fast weight filter frequency | Cut-off frequency of alternate weight path filter | read/ write | Float 32 | 0x415 | 0x01 | OxOB | 0, 1 | 0x425B | х | Х | х |
| Disable weight display | 1 = weight display disabled 0 = weight display enabled | read/ write | Binary | 0x416 | 0x01 | 0x02 | 0, 1 | 0x4302 | Х | Х | Х |

| Command | Description | . Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | HWM ≥V3.0.4 | SPC | SPE |
|---------------------------------|---|----------------|-----------|----------------|---------------------|-----------------|-------------------------|----------------|----------------|-----|-----|
| Factory reset | Reset all settings to factory defaults. | write | Uint 16 | 0x416 | 0x01 | OxOA | 0, 1 | 0x430A | 210.0.1 | Х | Х |
| Readability | Increases the indication scale interval (i) up to factor 1000 relative to the actual scale interval (d). The default indication scale interval equals the actual scale interval (factor 1). Parameter: 0 = Factor 1 1 = Factor 10 2 = Factor 100 3 = Factor 1000 4 = Factor 2 5 = Factor 5 | read/ write | Float 32 | 0x416 | 0x01 | OxOB | 0, 1 | 0x430B | X | Х | x |
| Gets and sets the date and time | Set or query the balance system date and time in a single action. (in unix timestamp) | Read/ write | Uint 32 | 0x416 | 0x01 | 0x11 | 0, 1 | 0x4311 | ≥V4.1.0 | Х | |
| General timeout | Timeout for issued command Parameter: 0 – 65535 Seconds | read/ write | Float 32 | 0x417 | 0x01 | 0x01 | 0, 1 | 0x4351 | Х | Х | Х |
| Observation time for zero | Report observation time for zero Parameter: 0.1 – 4.0 Seconds | read/ write | Float 32 | 0x417 | 0x01 | 0x03 | 0, 1 | 0x4353 | Х | Х | Х |
| Tolerance for zero | Report stability limit for zero Parameter: 0.1 – 1000 smallest actual scale interval | read/ write | Float 32 | 0x417 | 0x01 | 0x04 | 0, 1 | 0x4354 | х | Х | х |
| Observation time for tare | Report observation time for tare Parameter: 0.1 – 4.0 Seconds | read/ write | Float 32 | 0x417 | 0x01 | 0x05 | 0, 1 | 0x4355 | Х | Х | Х |
| Tolerance for tare | Report stability limit for tare Parameter: 0.1 – 1000 smallest actual scale interval | read/ write | Float 32 | 0x417 | 0x01 | 0x06 | 0, 1 | 0x4356 | Х | Х | Х |

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|---|--|----------------|-----------|----------------|---------------------|-----------------|-------------------------|----------------|---------|-----|-----|
| Observation time for weighing | Report observation time for weighing Parameter: 0.1 – 4.0 Seconds | read/ write | Float 32 | 0x417 | 0x01 | 0x07 | 0, 1 | 0x4357 | Х | Х | Х |
| Tolerance for weighing | Report stability limit for weighing Parameter: 0.1 – 1000 smallest actual scale interval | read/ write | Float 32 | 0x417 | 0x01 | 0x08 | 0, 1 | 0x4358 | х | Х | х |
| d, increment | Smallest actual scale interval | read | Float 32 | 0x417 | 0x01 | 0x16 | 0, 1 | 0x4366 | Х | Х | Х |
| Nmax (Maximal capacity) | Scale/Sensor capacity | read | Float 32 | 0x417 | 0x01 | 0x17 | 0, 1 | 0x4367 | Х | Х | Х |
| Automatic zero tracking | Query status of auto zero tracking respectively enable / disable it. Parameter: 0 = Disabled 1 = Enabled | read/ write | Uint 8 | 0x417 | 0x01 | Ox1E | 0, 1 | 0x436E | Х | Х | Х |
| Zeroing at start-up | Enable / Disable zeroing mode at startup Parameter: 0 = Disabled 1 = Enabled | read/ write | Uint 8 | 0x417 | 0x01 | Ox1F | 0, 1 | 0x436F | Х | Х | х |
| Report/Write Adjustment Observation Time | Time in seconds in which the weight value must remain within tolerance to be regarded as stable during an adjustment. Parameter: 0.1-4.0 seconds | Read/ Write | Float 32 | 0x417 | 0x01 | 0x27 | 0,1 | 0x4377 | ≥V3.0.2 | Х | х |
| Report/Write Adjustment Stability limit | Tolerance for the fluctuation of the weight value to still be regarded as stable during an adjustment Reported in digits (smallest actual scale interval) Parameter: 0.1-1000 d | Read/ Write | Float 32 | 0x417 | 0x01 | 0x28 | 0,1 | 0x4378 | ≥V3.0.2 | Х | Х |

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|--------------------------------------|--|------------|---------------|----------------|---------------------|-----------------|-------------------------|----------------|---------|-----|-----|
| Smallest Actual Scale Interval | Smallest actual scale interval in definition unit | Read | Float 32 | 0x417 | 0x01 | 0x29 | 0.1 | 0x4379 | ≥V4.1.0 | Х | |
| Trigger Initial Zero | Set new initial zero, where a device restart is not feasible. For status refer to "get initial zero information" | Write | Uint 8 | 0x417 | 0x01 | 0x2A | 0.1 | 0x437A | ≥V4.1.0 | Х | |
| USTB Observation Time Value Range | Provides the value range of the USTB Time parameter (seconds) | Read | Struct 64 | 0x417 | 0x01 | 0x2B | 0, 1 | 0x437B | ≥V4.1.0 | Х | |
| Active Stability Criteria | Returns the active stability criteria. Stability criteria is the interval the weight values must be located (stability limit) during the observation time for the weight value to be described as stable, or no- motion. | Read | Struct 256 | 0x417 | 0x01 | 0x2C | 0, 1 | 0x437C | ≥V4.1.0 | Х | |
| Report Target weight | Report Target Weight | read | Float 32 | 0x419 | 0x01 | 0x10 | 0, 1 | 0x4460 | Х | Х | Х |
| Read float32 | Test floating point variable – always reads 123.45 – no write permitted | read | Float 32 | 0x30F | 0x01 | 0x01 | 0, 1 | 0x5000 | х | Х | х |
| Write float32 | Test floating point variable – no usage in device except for test | write | Float 32 | 0x30F | 0x01 | 0x02 | 0, 0 | 0x5001 | х | Х | х |
| Read uint16 | Test integer variable – always reads 9876 | read | Uint 16 | 0x30F | 0x01 | 0x03 | 0, 1 | 0x5002 | Х | Х | Х |
| Write uint16 | Test integer variable – no usage in device except for test | write | Uint 16 | 0x30F | 0x01 | 0x04 | 0, 1 | 0x5003 | х | Х | х |
| Read string | Test string variable – always read "ABCD" | read | String 160 | 0x30F | 0x01 | 0x05 | 0, 1 | 0x5004 | х | Х | х |
| Write string | Test string variable – always read "ABCD" | write | String 160 | 0x30F | 0x01 | 0x06 | 0, 1 | 0x5005 | х | Х | х |
| Read uint32 | Test long integer variable – always reads 98765 | read | Uint 32 | 0x30F | 0x01 | 0x07 | 0, 1 | 0x5006 | Х | Х | Х |
| Write uint32 | Test long integer variable – no usage in device except for test | write | Uint 32 | 0x30F | 0x01 | 0x08 | 0, 1 | 0x5007 | Х | Х | Х |

| Command | Description | Read/Write | Data Type | EIP Class Code | EIP Instance Values | EIP Attribute # | Profinet slot + subslot | Profinet Index | WMF | SPC | SPE |
|-------------|---|------------|-----------|----------------|---------------------|-----------------|-------------------------|----------------|-----|-----|-----|
| Read uint8 | Test byte variable – always reads 56h | read | Uint 8 | 0x30F | 0x01 | 0x09 | 0, 1 | 0x5008 | Х | Х | Х |
| Write uint8 | Test byte variable – no usage in device except for test | write | Uint 8 | 0x30F | 0x01 | 0x10 | 0, 1 | 0x5009 | Х | Х | Х |

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